

**WHAT IS CLAIMED IS:**

1       1. A method of flat-field calibrating an image  
2       comprising:

3           obtaining a plurality of images  
4           performing linear regression on the plurality of images  
5       to obtain a gain and an offset; and

6           determining the desired image using the gain and the  
7       offset.

1       2. The method of Claim 1, further comprising obtaining  
2       a plurality of images ranging from dark current to full-well.

1       3. The method of Claim 1, further comprising performing  
2       linear regression on each pixel of the plurality of images.

1       4. The method of Claim 1, further comprising  
2       calculating the desired image using the equation:

3           Desired\_image = (Measured\_image - offset\_map) / gain\_map.

1       5. The method of Claim 1, further comprising moving a  
2       calibration slide while obtaining the plurality of images.

1       6. A method of reducing offset map noise comprising:

2       obtaining a plurality of images

3           obtaining the average dark current of the plurality of  
4           images; and

5           determining the desired image using the gain and the  
6           average dark current.

1           7. The method of Claim 6, further comprising obtaining  
2           a plurality of images ranging from dark current to full-well.

1           8. The method of Claim 6, further comprising  
2           calculating the desired image using the equation:

3           Desired\_image = (Measured\_image - average dark current) /  
4           gain\_map.

1           9. The method of Claim 6, further comprising averaging  
2           multiple frames to determine the desired image.

1           10. A method of reducing field curvature in an image  
2           comprising:

3           obtaining an average curvature map of a plurality of  
4           image panels;

5           dividing each panel by the curvature map.

1           11. The method of Claim 10, further comprising  
2           normalizing the curvature map by the average intensity of the  
3           curvature map.

1           12. The method of Claim 10, further comprising smoothing  
2           the curvature map.

1           13. The method of Claim 10, further comprising using  
2           only pixels above a background intensity to obtain the average  
3           curvature map.

1           14. The method of Claim 10, further comprising reducing  
2           noise in the image by curve-fitting the image pixels.

1           15. A method of reducing discontinuities between  
2           adjacent panels in an image comprising:

3           3        comparing a border of each panel on all sides to generate  
4           border intensity scaling values; and

5           5        scaling a boundary of each panel to a point approximately  
6           midway between a current panel and an adjacent panel.

1           16. The method of Claim 15, further comprising scaling  
2           the boundary of each panel using an inverse square weighting.

1           17. The method of Claim 15, further comprising scaling  
2           the boundary of each panel using an inverse weighting.